36Mb QDRII SRAM Specification

165 FBGA with Pb & Pb-Free (RoHS compliant)

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Document Title

1Mx36-bit, 2Mx18 and 4Mx9-bit QDR™ II b4 SRAM

Revision History

Rev. No.	<u>History</u>	Draft Date	<u>Remark</u>
0.0	1. Initial document.	Jan. 17, 2006	Advance
0.1	Put the data in the table of DC Characteristics, Pin Capacitance and Thermal Resistance.	Apr. 26. 2006	Preliminary
0.2	Add 300MHz Bin Change AC Characteristics.	May. 4. 2006	Preliminary
0.3	1. Change Samsung JEDEC Code in ID REGISTER DEFINITION	Jun. 05, 2006	Preliminary
0.4	1. Add x9 Organization.	Jun. 15, 2006	Preliminary
1.0	Final Change Vss/SA to NC/SA in Pin Configuration	Jul. 10, 2006	Final
1.1	1. Correct typo	Aug. 23, 2006	Final



1Mx36-bit, 2Mx18 and 4Mx9-bit QDR™ II b4 SRAM

FEATURES

- 1.8V+0.1V/-0.1V Power Supply.
- DLL circuitry for wide output data valid window and future frequency scaling.
- I/O Supply Voltage 1.5V+0.1V/-0.1V for 1.5V I/O, 1.8V+0.1V/-0.1V for 1.8V I/O.
- · Separate independent read and write data ports with concurrent read and write operation
- · HSTL I/O
- Full data coherency, providing most current data.
- · Synchronous pipeline read with self timed late write.
- · Registered address, control and data input/output.
- DDR (Double Data Rate) Interface on read and write ports.
- Fixed 4-bit burst for both read and write operation.
- Clock-stop supports to reduce current.
- Two input clocks (K and K) for accurate DDR timing at clock rising edges only.
- Two input clocks for output data (C and \overline{C}) to minimize clock-skew and flight-time mismatches.
- Two echo clocks (CQ and CQ) to enhance output data traceability.
- · Single address bus.
- Byte write (x9, x18, x36) function.
- Separate read/write control pin (R and W)
- · Simple depth expansion with no data contention.
- Programmable output impedance.
- JTAG 1149.1 compatible test access port.
- 165FBGA(11x15 ball array) with body size of 15mmx17mm.
- · Operating in commercial and industrial temperature range.

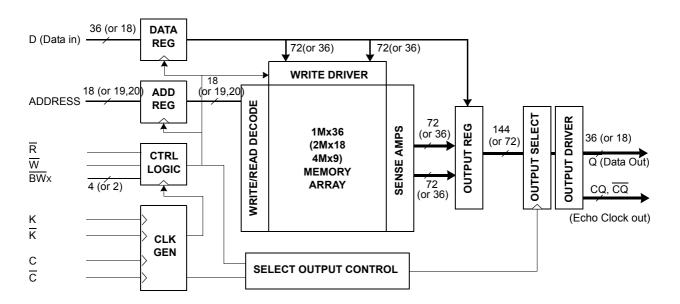
Org.	Part Number	Cycle Time	Access Time	Unit
	K7R323684C-F(E)C(I)33	3.0	0.45	ns
X36	K7R323684C-F(E)C(I)30	3.3	0.45	ns
	K7R323684C-F(E)C(I)25	4.0	0.45	ns
	K7R321884C-F(E)C(I)33	3.0	0.45	ns
X18	K7R321884C-F(E)C(I)30	3.3	0.45	ns
	K7R321884C-F(E)C(I)25	4.0	0.45	ns
	K7R320984C-F(E)C(I)33	3.0	0.45	ns
X9	K7R320984C-F(E)C(I)30	3.3	0.45	ns
	K7R320984C-F(E)C(I)25	4.0	0.45	ns

* -F(E)C(I)

F(E) [Package type]: E-Pb Free, F-Pb

C(I) [Operating Temperature]: C-Commercial, I-Industrial

FUNCTIONAL BLOCK DIAGRAM



Notes: 1. Numbers in () are for x18,x9 device



PIN CONFIGURATIONS(TOP VIEW) K7R323684C(1Mx36)

	1	2	3	4	5	6	7	8	9	10	11
Α	CQ	NC/SA*	NC/SA*	W	BW ₂	K	BW ₁	R	SA	NC/SA*	CQ
В	Q27	Q18	D18	SA	BW ₃	K	BW ₀	SA	D17	Q17	Q8
С	D27	Q28	D19	Vss	SA	NC	SA	Vss	D16	Q7	D8
D	D28	D20	Q19	Vss	Vss	Vss	Vss	Vss	Q16	D15	D7
Е	Q29	D29	Q20	VDDQ	Vss	Vss	Vss	VDDQ	Q15	D6	Q6
F	Q30	Q21	D21	VDDQ	VDD	Vss	VDD	VDDQ	D14	Q14	Q5
G	D30	D22	Q22	VDDQ	VDD	Vss	VDD	VDDQ	Q13	D13	D5
Н	Doff	VREF	VDDQ	VDDQ	VDD	Vss	VDD	VDDQ	VDDQ	VREF	ZQ
J	D31	Q31	D23	VDDQ	VDD	Vss	VDD	VDDQ	D12	Q4	D4
K	Q32	D32	Q23	VDDQ	VDD	Vss	VDD	VDDQ	Q12	D3	Q3
L	Q33	Q24	D24	VDDQ	Vss	Vss	Vss	VDDQ	D11	Q11	Q2
М	D33	Q34	D25	Vss	Vss	Vss	Vss	Vss	D10	Q1	D2
N	D34	D26	Q25	Vss	SA	SA	SA	Vss	Q10	D9	D1
Р	Q35	D35	Q26	SA	SA	С	SA	SA	Q9	D0	Q0
R	TDO	TCK	SA	SA	SA	C	SA	SA	SA	TMS	TDI

Notes: 1. * Checked No Connect (NC) pins are reserved for higher density address, i.e. 3A for 72Mb, 10A for 144Mb and 2A for 288Mb. 2. \overline{BW}_0 controls write to D0:D8, \overline{BW}_1 controls write to D9:D17, \overline{BW}_2 controls write to D18:D26 and \overline{BW}_3 controls write to D27:D35.

PIN NAME

SYMBOL	PIN NUMBERS	DESCRIPTION	NOTE
K, K	6B, 6A	Input Clock	
C, C	6P, 6R	Input Clock for Output Data	1
CQ, CQ	11A, 1A	Output Echo Clock	
Doff	1H	DLL Disable when low	
SA	9A,4B,8B,5C,7C,5N-7N,4P,5P,7P,8P,3R-5R,7R-9R	Address Inputs	
D0-35	10P,11N,11M,10K,11J,11G,10E,11D,11C,10N,9M,9L 9J,10G,9F,10D,9C,9B,3B,3C,2D,3F,2G,3J,3L,3M,2N 1C,1D,2E,1G,1J,2K,1M,1N,2P	Data Inputs	
Q0-35	11P,10M,11L,11K,10J,11F,11E,10C,11B,9P,9N,10L 9K,9G,10F,9E,9D,10B,2B,3D,3E,2F,3G,3K,2L,3N 3P,1B,2C,1E,1F,2J,1K,1L,2M,1P	Data Outputs	
W	4A	Write Control Pin, active when low	
R	8A	Read Control Pin, active when low	
BW0, BW1,BW2, BW3	7B,7A,5A,5B	Block Write Control Pin, active when low	
VREF	2H,10H	Input Reference Voltage	
ZQ	11H	Output Driver Impedance Control Input	2
VDD	5F,7F,5G,7G,5H,7H,5J,7J,5K,7K	Power Supply (1.8 V)	
VDDQ	4E,8E,4F,8F,4G,8G,3H,4H,8H,9H,4J,8J,4K,8K,4L,8L	Output Power Supply (1.5V or 1.8V)	
Vss	4C,8C,4D-8D,5E-7E,6F,6G,6H,6J,6K,5L-7L,4M, 8M,4N,8N	Ground	
TMS	10R	JTAG Test Mode Select	
TDI	11R	JTAG Test Data Input	
TCK	2R	JTAG Test Clock	
TDO	1R	JTAG Test Data Output	
NC	2A,3A,10A,6C	No Connect	3

Notes: 1. C, \overline{C} , K or \overline{K} cannot be set to VREF voltage.



^{2.} When ZQ pin is directly connected to VDD output impedance is set to minimum value and it cannot be connected to ground or left unconnected.

3. Not connected to chip pad internally.

PIN CONFIGURATIONS (TOP VIEW) K7R321884C (2Mx18)

	1	2	3	4	5	6	7	8	9	10	11
Α	CQ	NC/SA*	SA	W	BW ₁	K	NC	R	SA	NC/SA*	CQ
В	NC	Q9	D9	SA	NC	K	BW ₀	SA	NC	NC	Q8
С	NC	NC	D10	Vss	SA	NC	SA	Vss	NC	Q7	D8
D	NC	D11	Q10	Vss	Vss	Vss	Vss	Vss	NC	NC	D7
Е	NC	NC	Q11	VDDQ	Vss	Vss	Vss	VDDQ	NC	D6	Q6
F	NC	Q12	D12	VDDQ	VDD	Vss	VDD	VDDQ	NC	NC	Q5
G	NC	D13	Q13	VDDQ	VDD	Vss	VDD	VDDQ	NC	NC	D5
н	Doff	VREF	VDDQ	VDDQ	VDD	Vss	VDD	VDDQ	VDDQ	VREF	ZQ
J	NC	NC	D14	VDDQ	VDD	Vss	VDD	VDDQ	NC	Q4	D4
K	NC	NC	Q14	VDDQ	VDD	Vss	VDD	VDDQ	NC	D3	Q3
L	NC	Q15	D15	VDDQ	Vss	Vss	Vss	VDDQ	NC	NC	Q2
М	NC	NC	D16	Vss	Vss	Vss	Vss	Vss	NC	Q1	D2
N	NC	D17	Q16	Vss	SA	SA	SA	Vss	NC	NC	D1
Р	NC	NC	Q17	SA	SA	С	SA	SA	NC	D0	Q0
R	TDO	TCK	SA	SA	SA	C	SA	SA	SA	TMS	TDI

Notes: 1. * Checked No Connect (NC) pins are reserved for higher density address, i.e. 10A for 72Mb and 2A for 144Mb. 2. \overline{BW}_0 controls write to D0:D8 and \overline{BW}_1 controls write to D9:D17.

PIN NAME

SYMBOL	PIN NUMBERS	DESCRIPTION	NOTE
K, K	6B, 6A	Input Clock	
C, $\overline{\overline{C}}$	6P, 6R	Input Clock for Output Data	1
CQ, CQ	11A, 1A	Output Echo Clock	
Doff	1H	DLL Disable when low	
SA	3A,9A,4B,8B,5C,7C,5N-7N,4P,5P,7P,8P,3R-5R,7R-9R	Address Inputs	
D0-17	10P,11N,11M,10K,11J,11G,10E,11D,11C,3B,3C,2D 3F,2G,3J,3L,3M,2N	Data Inputs	
Q0-17	11P,10M,11L,11K,10J,11F,11E,10C,11B,2B,3D,3E 2F,3G,3K,2L,3N,3P	Data Outputs	
W	4A	Write Control Pin, active when low	
R	8A	Read Control Pin, active when low	
BW ₀ , BW ₁	7B, 5A	Block Write Control Pin, active when low	
VREF	2H,10H	Input Reference Voltage	
ZQ	11H	Output Driver Impedance Control Input	2
VDD	5F,7F,5G,7G,5H,7H,5J,7J,5K,7K	Power Supply (1.8 V)	
VDDQ	4E,8E,4F,8F,4G,8G,3H,4H,8H,9H,4J,8J,4K,8K,4L,8L	Output Power Supply (1.5V or 1.8V)	
Vss	4C,8C,4D-8D,5E-7E,6F,6G,6H,6J,6K,5L-7L,4M-8M,4N,8N	Ground	
TMS	10R	JTAG Test Mode Select	
TDI	11R	JTAG Test Data Input	
TCK	2R	JTAG Test Clock	
TDO	1R	JTAG Test Data Output	
NC	2A,10A,7A,1B,5B,9B,10B,1C,2C,6C,9C,1D,9D,10D,1E,2E,9E,1F 9F,10F,1G,9G,10G,1J,2J,9J,1K,2K,9K,1L,9L,10L,1M 2M,9M,1N,9N,10N,1P,2P,9P	No Connect	3

Notes: 1. C, \overline{C} , K or \overline{K} cannot be set to VREF voltage.

2. When ZQ pin is directly connected to VDD output impedance is set to minimum value and it cannot be connected to ground or left unconnected.

3. Not connected to chip pad internally.



PIN CONFIGURATIONS (TOP VIEW) K7R360984C(4Mx9)

	1	2	3	4	5	6	7	8	9	10	11
Α	CQ	NC/SA*	SA	\overline{W}	NC	K	NC	R	SA	SA	CQ
В	NC	NC	NC	SA	NC	K	BW	SA	NC	NC	Q3
С	NC	NC	NC	Vss	SA	NC	SA	Vss	NC	NC	D3
D	NC	D4	NC	Vss	Vss	Vss	Vss	Vss	NC	NC	NC
E	NC	NC	Q4	VDDQ	Vss	Vss	Vss	VDDQ	NC	D2	Q2
F	NC	NC	NC	VDDQ	Vdd	Vss	VDD	VDDQ	NC	NC	NC
G	NC	D5	Q5	VDDQ	Vdd	Vss	VDD	VDDQ	NC	NC	NC
н	Doff	VREF	VDDQ	VDDQ	VDD	Vss	VDD	VDDQ	VDDQ	VREF	ZQ
J	NC	NC	NC	VDDQ	Vdd	Vss	VDD	VDDQ	NC	Q1	D1
K	NC	NC	NC	VDDQ	Vdd	Vss	VDD	VDDQ	NC	NC	NC
L	NC	Q6	D6	VDDQ	Vss	Vss	Vss	VDDQ	NC	NC	Q0
М	NC	NC	NC	Vss	Vss	Vss	Vss	Vss	NC	NC	D0
N	NC	D7	NC	Vss	SA	SA	SA	Vss	NC	NC	NC
Р	NC	NC	Q7	SA	SA	С	SA	SA	NC	D8	Q8
R	TDO	TCK	SA	SA	SA	c	SA	SA	SA	TMS	TDI

Notes: 1. * Checked No Connect (NC) pins are reserved for higher density address, i.e. 2A for 72Mb. 2. \overline{BW} controls write to D0:D8.

PIN NAME

SYMBOL	PIN NUMBERS	DESCRIPTION	NOTE
K, K	6B, 6A	Input Clock	
C, \overline{C}	6P, 6R	Input Clock for Output Data	1
CQ, \overline{CQ}	11A, 1A	Output Echo Clock	
Doff	1H	DLL Disable when low	
SA	3A,9A,10A,4B,8B,5C,7C,5N-7N,4P,5P,7P,8P,3R-5R,7R-9R	Address Inputs	
D0-8	11M,11J,10E,11C,2D,2G,3L,2N,10P	Data Inputs	
Q0-8	11L,10J,11E,11B,3E,3G,2L,3P,11P	Data Outputs	
W	4A	Write Control Pin, active when low	
R	8A	Read Control Pin, active when low	
BW	7B	Nybble Write Control Pin, active when low	
VREF	2H,10H	Input Reference Voltage	
ZQ	11H	Output Driver Impedance Control Input	2
VDD	5F,7F,5G,7G,5H,7H,5J,7J,5K,7K	Power Supply (1.8 V)	
VDDQ	4E,8E,4F,8F,4G,8G,3H,4H,8H,9H,4J,8J,4K,8K,4L,8L	Output Power Supply (1.5V or 1.8V)	
Vss	4C,8C,4D-8D,5E-7E,6F,6G,6H,6J,6K,5L-7L,4M-8M,4N,8N	Ground	
TMS	10R	JTAG Test Mode Select	
TDI	11R	JTAG Test Data Input	
TCK	2R	JTAG Test Clock	
TDO	1R	JTAG Test Data Output	
NC	2A,7A,5A,1B,2B,3B,5B,9B,10B,1C,2C,3C,6C,9C,10C,1D,3D,9D, 10D,11D,1E,2E,9E,1F,2F,3F,9F,10F,11F,1G,9G,10G,11G,1J,2J, 3J,9J,1K,2K,3K,10K,11K,9K,1L,9L,10L,1M,2M,3M,9M,10M,1N,3N ,9N,10N,11N,1P,2P,9P	No Connect	3

Notes: 1. C, \overline{C} , K or \overline{K} cannot be set to VREF voltage.

2. When ZQ pin is directly connected to VDD output impedance is set to minimum value and it cannot be connected to ground or left unconnected.

3. Not connected to chip pad internally.



GENERAL DESCRIPTION

The K7R323684C, K7R321884C and K7R320984C are 37,748,736-bits QDR (Quad Data Rate) Synchronous Pipelined Burst SRAMs. They are organized as 1,048,576 words by 36bits for K7R323684C and 2,097,152 words by 18 bits for K7R321884C and 4,194,304 words by 9 bits for K7R320984C.

The QDR operation is possible by supporting DDR read and write operations through separate data output and input ports with the same cycle. Memory bandwidth is maximized as data can be transferred into SRAM on every rising edge of K and \overline{K} , and transferred out of SRAM on every rising edge of C and \overline{C} . And totally independent read and write ports eliminate the need for high speed bus turn around

Address for read and write are latched on alternate rising edges of the input clock K. Data inputs, and all control signals are synchronized to the input clock (K or \overline{K}). Normally data outputs are synchronized to output clocks (C and \overline{C}), but when C and \overline{C} are tied high, the data outputs are synchronized to the input clocks (K and \overline{K}). Read data are referenced to echo clock (CQ or \overline{CQ}) outputs.

Common address bus is used to access address both for read and write operations. The internal burst counter is fixed to 4-bit sequential for both read and write operations, requiring tow full clock bus cycles. Any request that attempts to interrupt a burst operation in progress is ignored. Synchronous pipeline read and late write enable high speed operations. Simple depth expansion is accomplished by using \overline{R} and \overline{W} for port selection. Byte write operation is supported with $\overline{BW_0}$ and $\overline{BW_1}$ ($\overline{BW_2}$ and $\overline{BW_3}$) pins. IEEE 1149.1 serial boundary scan (JTAG) simplifies monitoring package pads attachment status with system.

The K7R323684C, K7R321884C and K7R320984C are implemented with SAMSUNG's high performance 6T CMOS technology and is available in 165pin FBGA packages. Multiple power and ground pins minimize ground bounce.

Read Operations

Read cycles are initiated by activating \overline{R} at the rising edge of the positive input clock K. Address is presented and stored in the read address register synchronized with K clock. For 4-bit burst DDR operation, it will access four 36-bit, 18-bit or 9-bit data words with each read command

The first pipelined data is transferred out of the device triggered by \overline{C} clock following next \overline{K} clock rising edge. Next burst data is triggered by the rising edge of following C clock rising edge. The process continues until all four data are transferred. Continuous read operations are initiated with K clock rising edge. And pipelined data are transferred out of device on every rising edge of both C and \overline{C} clocks. In case C and \overline{C} tied to high, output data are triggered by K and \overline{K} instead of C and \overline{C} .

When the \overline{R} is disabled after a read operation, the K7R323684C, K7R321884C and K7R320984C will first complete burst read operation before entering into deselect mode at the next K clock rising edge. Then output drivers disabled automatically to high impedance state.

Write Operations

Write cycles are initiated by activating \overline{W} at the rising edge of the positive input clock K. Address is presented and stored in the write address register synchronized with K clock. For 4-bit burst DDR operation, it will write four 36-bit, 18-bit or 9-bit data words with each write command

The first "late" data is transferred and registered in to the device synchronous with next K clock rising edge. Next burst data is transferred and registered synchronous with following \overline{K} clock rising edge. The process continues until all four data are transferred and registered. Continuous write operations are initiated with K rising edge. And "late write" data is presented to the device on every rising edge of both K and \overline{K} clocks.

The device disregards input data presented on the same cycle \overline{W} disabled. When the \overline{W} is disabled after a read operation, the K7R323684C, K7R321884C and K7R320984C will first complete burst read operation before entering into deselect mode at the next K clock rising edge.

The K7R323684C, K7R321884C and K7R320984C support byte write operations. With activating $\overline{BW_0}$ or $\overline{BW_1}$ ($\overline{BW_2}$ or $\overline{BW_3}$) in write cycle, only one byte of input data is presented. In K7R321884C, $\overline{BW_0}$ controls write operation to D0:D8, $\overline{BW_1}$ controls write operation to D9:D17. And in K7R323684C $\overline{BW_2}$ controls write operation to D18:D26, $\overline{BW_3}$ controls write operation to D27:D35. And in K7R320984C \overline{BW} controls write operation to D0:D8.



Single Clock Mode

The K7R323684C, K7R321884C and K7R320984C can be operated with the single clock pair K and \overline{K} , instead of C or \overline{C} for output clocks. To operate these devices in single clock mode, C and \overline{C} must be tied high during power up and must be maintained high during operation. After power up, this device can't change to or from single clock mode. System flight time and clock skew could not be compensated in this mode.

Depth Expansion

Separate input and output ports enables easy depth expansion. Each port can be selected and deselected independently and read and write operation do not affect each other. Before chip deselected, all read and write pending operations are completed.

Programmable Impedance Output Buffer Operation

The designer can program the SRAM's output buffer impedance by terminating the ZQ pin to Vss through a precision resistor(RQ). The value of RQ (within 15%) is five times the output impedance desired. For example, 250Ω resistor will give an output impedance of 50Ω

Impedance updates occur early in cycles that do not activate the outputs, such as deselect cycles. In all cases impedance updates are transparent to the user and do not produce access time "push-outs" or other anomalous behavior in the SRAM.

There are no power up requirements for the SRAM. However, to guarantee optimum output driver impedance after power up, the SRAM needs 1024 non-read cycles.

Echo clock operation

To assure the output traceability, the SRAM provides the output Echo clock, pair of compliment clock CQ and \overline{CQ} , which are synchronized with internal data output. Echo clocks run free during normal operation.

The Echo clock is triggered by internal output clock signal, and transferred to external through same structures as output driver.

Clock Consideration

K7R323684C, K7R321884C and K7R320984C utilizes internal DLL (Delay-Locked Loops) for maximum output data valid window. It can be placed into a stopped-clock state to minimize power with a modest restart time of 1024 clock cycles. Circuitry automatically resets the DLL when absence of input clock is detected.

Power-Up/Power-Down Supply Voltage Sequencing

The following power-up supply voltage application is recommended: VSS, VDD, VDDQ, VREF, then VIN. VDD and VDDQ can be applied simultaneously, as long as VDDQ does not exceed VDD by more than 0.5V during power-up. The following power-down supply voltage removal sequence is recommended: VIN, VREF, VDDQ, VDD, VSS. VDD and VDDQ can be removed simultaneously, as long as VDDQ does not exceed VDD by more than 0.5V during power-down.



Detail Specification of Power-Up Sequence in QDRII SRAM

QDRII SRAMs must be powered up and initialized in a predefined manner to prevent undefined operations.

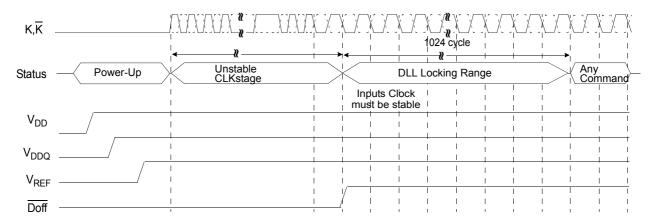
Power-Up Sequence

- 1. Apply power and keep Doff at low state (All other inputs may be undefined)
 - Apply VDD before VDDQ
 - Apply VDDQ before VREF or the same time with VREF
- 2. Just after the stable power and clock (K, \overline{K} , C, \overline{C}), take $\overline{\text{Doff}}$ to be high.
- 3. The additional 1024cycles of clock input is required to lock the DLL after enabling DLL
 - * **Notes**: If you want to tie up the Doff pin to High with unstable clock, then you must stop the clock for a few seconds (Min. 30ns) to reset the DLL after it become a stable clock status.

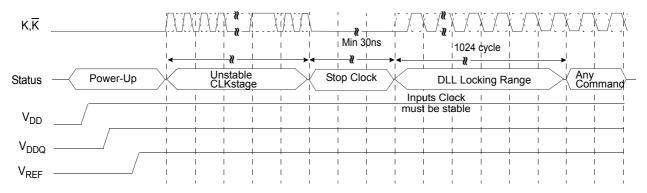
DLL Constraints

- 1. DLL uses either K or C clock as its synchronizing input, the input should have low phase jitter which is specified as TKC var.
- 2. The lower end of the frequency at which the DLL can operate is 8.4ns.
- 3. If the incoming clock is unstable and the DLL is enabled, then the DLL may lock onto a wrong frequency and this may cause the failure in the initial stage.

Power up & Initialization Sequence (Doff pin controlled)



Power up & Initialization Sequence (Doff pin Fixed high, Clock controlled)



^{*} Notes: When the operating frequency is changed, DLL reset should be required again.

After DLL reset again, the minimum 1024 cycles of clock input is needed to lock the DLL.



TRUTH TABLES

SYNCHRONOUS TRUTH TABLE

K	R		D					()		OPERATION
, ,	IX.		D(A1)	D(A2)	D(A3)	D(A4)	Q(A1)	Q(A2)	Q(A3)	Q(A4)	OPERATION
Stopped	X	X	Previous state	Previous state	Previous state	Previous state	Previous state	Previous state	Previous state	Previous state	Clock Stop
1	Н	Н	Х	Х	Х	Х	High-Z	High-Z	High-Z	High-Z	No Operation
↑	L ⁴	Х	х	Х	Х	Х	<u>D</u> оит at C(t+1)	Douт at C(t+2)	<u>D</u> оит at \overline{C} (t+2)	Dout at C(t+3)	Read
↑	H ⁵	L ⁴	Din at K(t+1)	<u>D</u> in at K(t+1)	Din at K(t+2)	<u>D</u> in at K(t+2)	Х	х	Х	Х	Write

Notes: 1. X means "Don't Care".

- 2. The rising edge of clock is symbolized by (\uparrow).
- 3. Before enter into clock stop status, all pending read and write operations will be completed.
- 4. This signal was HIGH on previous K clock rising edge. Initiating consecutive READ or WRITE operations on consecutive K clock rising edges is not permitted. The device will ignore the second request.
- 5. If this signal was LOW to initiated the previous cycle, this signal becomes a don't care for this operation however it is strongly recommended that this signal is brought HIGH as shown in the truth table.

WRITE TRUTH TABLE(x18)

K	ĸ	BW ₀	BW ₁	OPERATION
↑		L	L	WRITE ALL BYTEs (K↑)
	↑	L	L	WRITE ALL BYTEs (K↑)
↑		L	Н	WRITE BYTE 0 (K↑)
	↑	L	Н	WRITE BYTE 0 (K↑)
↑		Н	L	WRITE BYTE 1 (K↑)
	↑	Н	L	WRITE BYTE 1 (K↑)
↑		Н	Н	WRITE NOTHING (K↑)
	↑	Н	Н	WRITE NOTHING ($\overline{\mathbf{K}}$)

Notes: 1. X means "Don't Care".

- 2. All inputs in this table must meet setup and hold time around the rising edge of input clock K or \overline{K} (\uparrow).
- 3. Assumes a WRITE cycle was initiated.
- 4. This table illustrates operation for x18 devices. x9 device operation is similar except that \overline{BW} controls D0:D8.

WRITE TRUTH TABLE(x36)

K	K	BW ₀	BW ₁	BW ₂	BW ₃	OPERATION
↑		L	L	L	L	WRITE ALL BYTEs (K↑)
	↑	L	L	L	L	WRITE ALL BYTEs (K↑)
↑		L	Н	Н	Н	WRITE BYTE 0 (K↑)
	↑	L	Н	Н	Н	WRITE BYTE 0 (K↑)
↑		Н	L	Н	Н	WRITE BYTE 1 (K↑)
	↑	Н	L	Н	Н	WRITE BYTE 1 (K↑)
↑		Н	Н	L	L	WRITE BYTE 2 and BYTE 3 (K↑)
	↑	Н	Н	L	L	WRITE BYTE 2 and BYTE 3 ($\overline{K}\uparrow$)
↑		Н	Н	Н	Н	WRITE NOTHING (K↑)
	↑	Н	Н	Н	Н	WRITE NOTHING (K↑)

Notes: 1. X means "Don't Care".

- 2. All inputs in this table must meet setup and hold time around the rising edge of input clock K or \overline{K} (\uparrow).
- 3. Assumes a WRITE cycle was initiated.



ABSOLUTE MAXIMUM RATINGS*

PARAMETE	R	SYMBOL	RATING	UNIT
Voltage on VDD Supply Relative to Vss		VDD	-0.5 to 2.9	V
Voltage on VDDQ Supply Relative to Vss		VDDQ	-0.5 to VDD	V
Voltage on Input Pin Relative to Vss		VIN	-0.5 to VDD+0.3	V
Storage Temperature		Тѕтс	-65 to 150	°C
Operating Temperature	Commercial / Industrial	Topr	0 to 70 / -40 to 85	°C
Storage Temperature Range Under Bias		TBIAS	-10 to 85	°C

^{*}Note: 1. Stresses greater than those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions above those indicated in the operating sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect reliability.

OPERATING CONDITIONS

PARAMETER	SYMBOL	Min	MAX	UNIT
Supply Voltage	VDD		1.9	V
Supply Voltage	VDDQ	1.4	1.9	V
Reference Voltage	VREF	0.68	0.95	V

DC ELECTRICAL CHARACTERISTICS

PARAMETER	SYMBOL	TEST CONDITIONS		MIN	MAX	UNIT	NOTES
Input Leakage Current	lıL	VDD=Max; VIN=Vss to VDDQ		-2	+2	μΑ	
Output Leakage Current	loL	Output Disabled,		-2	+2	μΑ	
		No. Mary Issue Organ	-33	-	850		
Operating Current (x36)	Icc	VDD=Max, IOUT=0mA Cycle Time ≥ tkнkн Min	-30	-	800	mA	1,5
		Cycle Time 2 transferring	-25	-	750	ША	1,5
		V	-33	-	800		
Operating Current (x18)	Icc	VDD=Max, Iouт=0mA Cycle Time ≥ tкнкн Min	-30	-	750	m 1	1 5
		Cycle Time = tknkn iviiii	-25	-	700	mA	1,5
			-33	-	750		
Operating Current (x9)	Icc	Cycle Time ≥ tkhkh Min	-30	-	700	- mA	4.5
			-25	-	650		1,5
		Device development laws One A & Many	-33	-	350		
Standby Current (NOP)	ISB1	Device deselected, IouT=0mA, f=Max, All Inputs≤0.2V or ≥ VDD-0.2V	-30	-	330	Λ	1.0
		All Inputs 50.2 V OI 2 VDD-0.2 V	-25	-	300	mA	1,6
Output High Voltage	Vo _{H1}			VDDQ/2-0.12	VDDQ/2+0.12	V	2,7
Output Low Voltage	Vol1			VDDQ/2-0.12	VDDQ/2+0.12	V	3,7
Output High Voltage	Voh2	IOH=-1.0mA		VDDQ-0.2	VDDQ	V	4
Output Low Voltage	VOL2	IoL=1.0mA		Vss	0.2	V	4
Input Low Voltage	VIL			-0.3	VREF-0.1	V	8,9
Input High Voltage	VIH			VREF+0.1	VDDQ+0.3	V	8,10

Notes: 1. Minimum cycle. IOUT=0mA.

- 2. $|IOH| = (VDDQ/2)/(RQ/5) \pm 15\%$ for $175\Omega \le RQ \le 350\Omega$.
- 3. |IoL|= $(VDDQ/2)/(RQ/5)\pm15\%$ for $175\Omega \le RQ \le 350\Omega$.
- 4. Minimum Impedance Mode when ZQ pin is connected to $V_{\mbox{\scriptsize DD}}.$
- 5. Operating current is calculated with 50% read cycles and 50% write cycles.
- 6. Standby Current is only after all pending read and write burst operations are completed.
- 7. Programmable Impedance Mode.
- 8. These are DC test criteria. DC design criteria is VREF±50mV. The AC VIH/VIL levels are defined separately for measuring timing parameters.
- 9. VIL (Min) DC=-0.3V, VIL (Min) AC=-1.5V(pulse width \leq 3ns).
- 10. ViH (Max)DC=VDDQ+0.3, ViH (Max)AC=VDDQ+0.85V(pulse width ≤ 3ns)



^{2.} VDDQ must not exceed VDD during normal operation.

AC ELECTRICAL CHARACTERISTICS

PARAMETER	SYMBOL	MIN	MAX	UNIT	NOTES
Input High Voltage	VIH (AC)	VREF + 0.2	-	V	1,2
Input Low Voltage	VIL (AC)	-	VREF - 0.2	V	1,2

Notes: 1. This condition is for AC function test only, not for AC parameter test.

- 2. To maintain a valid level, the transiting edge of the input must:
 - a) Sustain a constant slew rate from the current AC level through the target AC level, VIL(AC) or VIH(AC)
- b) Reach at least the target AC level
- c) After the AC target level is reached, continue to maintain at least the target DC level, VIL(DC) or VIH(DC)

AC TIMING CHARACTERISTICS

PARAMETER SYMBOL		-	33	-3	30	-2	25		
PARAMETER	SYMBOL	MIN	MAX	MIN	MAX	MIN	MAX	UNIT	NOTE
Clock				•					
Clock Cycle Time (K, \overline{K} , C, \overline{C})	tкнкн	3.00	8.40	3.30	8.40	4.00	8.40	ns	
Clock Phase Jitter (K, K, C, C)	tKC var		0.20		0.20		0.20	ns	5
Clock High Time (K, K, C, C)	tkhkl	1.2		1.32		1.60		ns	
Clock Low Time (K, K, C, C)	tklkh	1.2		1.32		1.60		ns	
Clock to $\overline{\text{Clock}}$ (K $\uparrow \rightarrow \overline{\text{K}}\uparrow$, C $\uparrow \rightarrow \overline{\text{C}}\uparrow$)	tĸh ĸ h	1.35		1.49		1.80		ns	
Clock to data clock $(K\uparrow \to C\uparrow, \overline{K}\uparrow \to \overline{C}\uparrow)$	tкнсн	0.00	1.30	0.00	1.45	0.00	1.80	ns	
DLL Lock Time (K, C)	tKC lock	1024		1024		1024		cycle	6
K Static to DLL reset	tKC reset	30		30		30		ns	
Output Times									
C, C High to Output Valid	tchqv		0.45		0.45		0.45	ns	3
C, C High to Output Hold	tchqx	-0.45		-0.45		-0.45		ns	3
C, C High to Echo Clock Valid	tchcqv		0.45		0.45		0.45	ns	
C, C High to Echo Clock Hold	tchcqx	-0.45		-0.45		-0.45		ns	
CQ, CQ High to Output Valid	tсанаv		0.25		0.27		0.30	ns	7
CQ, CQ High to Output Hold	tсанах	-0.25		-0.27		-0.30		ns	7
C, High to Output High-Z	tchqz		0.45		0.45		0.45	ns	3
C, High to Output Low-Z	tcHQX1	-0.45		-0.45		-0.45		ns	3
Setup Times									
Address valid to K rising edge	tavkh	0.40		0.40		0.50		ns	
Control inputs valid to K rising edge	tıvkh	0.40		0.40		0.50		ns	2
Data-in valid to K, K rising edge	t DVKH	0.28		0.30		0.35		ns	
Hold Times									
K rising edge to address hold	tkhax	0.40		0.40		0.50		ns	
K rising edge to control inputs hold	tĸнıx	0.40	_	0.40		0.50		ns	
K, \overline{K} rising edge to data-in hold	tkhdx	0.28		0.30		0.35		ns	

Notes: 1. All address inputs <u>must meet the</u> specifi<u>ed setup</u> and hold times for <u>all la</u>tching clock edges.

- 2. Control singles are R, W,BWo,BW1 and (BW2, BW3, also for x36 and BW for x9)
- 3. If C,\overline{C} are tied high, K,\overline{K} become the references for C,\overline{C} timing parameters.
- 4. To avoid bus contention, at a given voltage and temperature tCHQX1 is bigger than tCHQZ.

 The specs as shown do not imply bus contention because tCHQX1 is a MIN parameter that is worst case at totally different test conditions (0°C, 1.9V) than tCHQZ, which is a MAX parameter (worst case at 70°C, 1.7V)

 It is not possible for two SRAMs on the same board to be at such different voltage and temperature.
- 5. Clock phase jitter is the variance from clock rising edge to the next expected clock rising edge.
- 6. Vdd slew rate must be less than 0.1V DC per 50 ns for DLL lock retention. DLL lock time begins once Vdd and input clock are stable.
- 7. Echo clock is very tightly controlled to data valid/data hold. By design, there is a ± 0.1 ns variation from echo clock to data. The data sheet parameters reflect tester guard bands and test setup variations.



THERMAL RESISTANCE

PRMETER	SYMBOL	TYP	Unit	NOTES
Junction to Ambient	θJΑ	20.8	°C/W	
Junction to Case	θјС	2.3	°C/W	
Junction to Pins	θЈВ	4.3	°C/W	

Note: Junction temperature is a function of on-chip power dissipation, package thermal impedance, mounting site temperature and mounting site thermal impedance. T_J=T_A + P_D x θ_{JA}

PIN CAPACITANCE

PRMETER	SYMBOL	TESTCONDITION	TYP	MAX	Unit	NOTES
Address Control Input Capacitance	CIN	VIN=0V	3.5	4	pF	
Input and Output Capacitance	Соит	Vout=0V	4	5	pF	
Clock Capacitance	Cclk	-	3	4	pF	

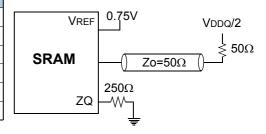
Note: 1. Parameters are tested with RQ=250 Ω and VDDQ=1.5V.

2. Periodically sampled and not 100% tested.

AC TEST CONDITIONS

AC TEST OUTPUT LOAD

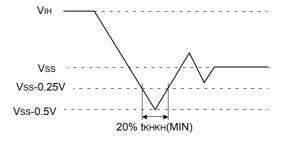
Parameter	Symbol	Value	Unit
Core Power Supply Voltage	Vdd	1.7~1.9	V
Output Power Supply Voltage	VDDQ	1.4~1.9	V
Input High/Low Level	VIH/VIL	1.25/0.25	V
Input Reference Level	VREF	0.75	V
Input Rise/Fall Time	Tr/Tf	0.3/0.3	ns
Output Timing Reference Level		VDDQ/2	V



Note: Parameters are tested with RQ=250 Ω

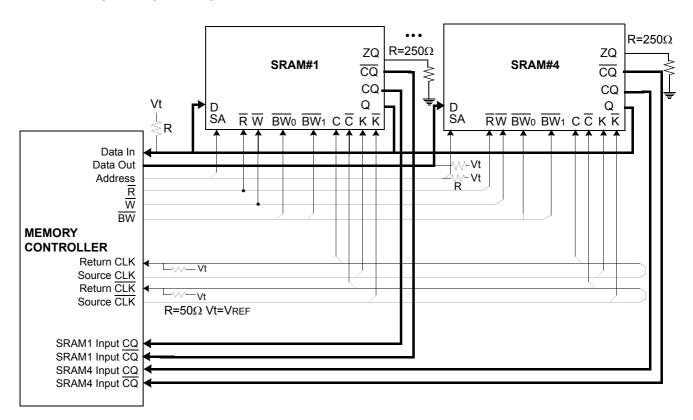
Overershoot Timing

Undershoot Timing



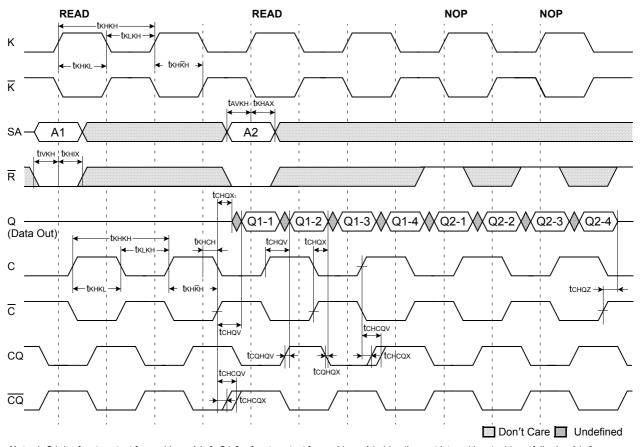
Note: For power-up, ViH \leq VdDQ+0.3V and VdD \leq 1.7V and VdDQ \leq 1.4V $t \leq$ 200ms

APPLICATION INRORMATION



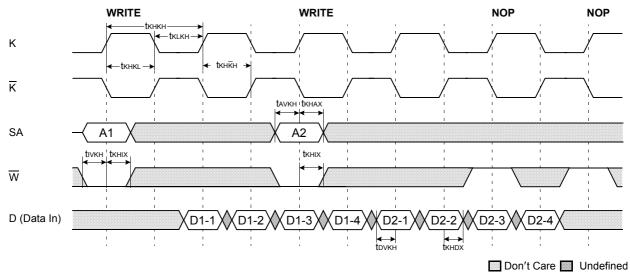


TIMING WAVE FORMS OF READ AND NOP



Note: 1. Q1-1 refers to output from address A1+0, Q1-2 refers to output from address A1+1 i.e. the next internal burst address following A1+0. 2. Outputs are disabled one cycle after a NOP.

TIMING WAVE FORMS OF WRITE AND NOP

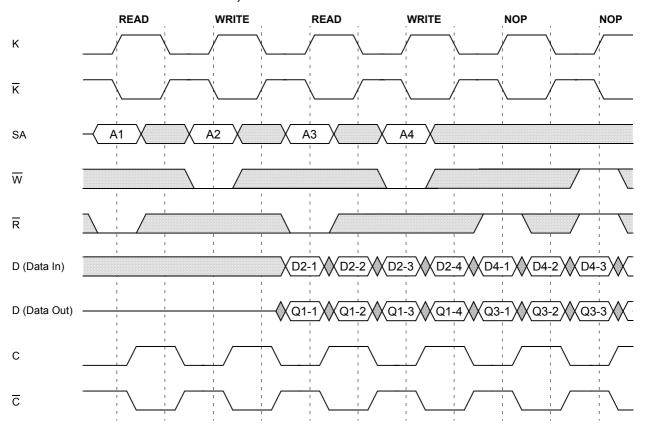


Note: 1. D1-1 refers to input to address A1+0, D1-2 refers to input to address A1+1, i.e the next internal burst address following A1+0.

2. BWx (NWx) assumed active.



TIMING WAVE FORMS OF READ, WRITE AND NOP



Note: 1. If address A3=A2, data Q3-1=D2-1, data Q3-2=D2-2, data Q3-3=D2-3, data Q3-4=D2-4 Write data is forwarded immediately as read results.

2.BWx (NWx) assumed active.

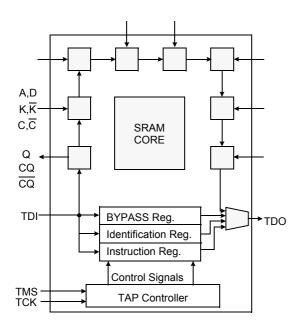


Don't Care Undefined

IEEE 1149.1 TEST ACCESS PORT AND BOUNDARY SCAN-JTAG

This part contains an IEEE standard 1149.1 Compatible Test Access Port (TAP). The package pads are monitored by the Serial Scan circuitry when in test mode. This is to support connectivity testing during manufacturing and system diagnostics. Internal data is not driven out of the SRAM under JTAG control. In conformance with IEEE 1149.1, the SRAM contains a TAP controller, Instruction Register, Bypass Register and ID register. The TAP controller has a standard 16-state machine that resets internally upon power-up, therefore, TRST signal is not required. It is possible to use this device without utilizing the TAP. To disable the TAP controller without interfacing with normal operation of the SRAM, TCK must be tied to Vss to preclude mid level input. TMS and TDI are designed so an undriven input will produce a response identical to the application of a logic 1, and may be left unconnected. But they may also be tied to VDD through a resistor. TDO should be left unconnected.

JTAG Block Diagram



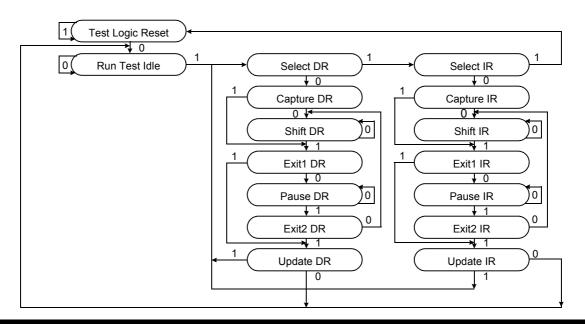
JTAG Instruction Coding

IR2	IR1	IR0	Instruction	TDO Output	Notes
0	0	0	EXTEST	Boundary Scan Register	1
0	0	1	IDCODE	Identification Register	3
0	1	0	SAMPLE-Z	Boundary Scan Register	2
0	1	1	RESERVED	Do Not Use	6
1	0	0	SAMPLE	Boundary Scan Register	5
1	0	1	RESERVED	Do Not Use	6
1	1	0	RESERVED	Do Not Use	6
1	1	1	BYPASS	Bypass Register	4

NOTE:

- Places DQs in Hi-Z in order to sample all input data regardless of other SRAM inputs. This instruction is not IEEE 1149.1 compliant.
- Places DQs in Hi-Z in order to sample all input data regardless of other SRAM inputs.
- TDI is sampled as an input to the first ID register to allow for the serial shift of the external TDI data.
- Bypass register is initiated to Vss when BYPASS instruction is invoked. The Bypass Register also holds serially loaded TDI when exiting the Shift DR states.
- 5. SAMPLE instruction dose not places DQs in Hi-Z.
- 6. This instruction is reserved for future use.

TAP Controller State Diagram





SCAN REGISTER DEFINITION

Part	Instruction Register	Bypass Register	ID Register	Boundary Scan
1Mx36	3 bits	1 bit	32 bits	109 bits
2Mx18	3 bits	1 bit	32 bits	109 bits
4Mx9	3 bits	1 bit	32 bits	109 bits

ID REGISTER DEFINITION

Part	Revision Number (31:29)	Part Configuration (28:12)	Samsung JEDEC Code (11: 1)	Start Bit(0)
1Mx36	000	00def0wx0t0q0b0s0	00011001110	1
2Mx18	000	00def0wx0t0q0b0s0	00011001110	1
4Mx9	000	00def0wx0t0q0b0s0	00011001110	1

Note: Part Configuration

/def=010 for 36Mb, /wx=11 for x36, 10 for x18 and 00 for x9 $\,$

/t=1 for DLL Ver., 0 for non-DLL Ver. /q=1 for QDR, 0 for DDR /b=1 for 4Bit Burst, 0 for 2Bit Burst /s=1 for Separate I/O, 0 for Common I/O

PIN ID

ORDER

BOUNDARY SCAN EXIT ORDER

PIN ID
6R
6P
6N
7P
7N
7R
8R
8P
9R
11P
10P
10N
9P
10M
11N
9M
9N
11L
11M
9L
10L
11K
10K
9J
9K
10J
11J
11H
10G
9G
11F
11G
9F
10F
11E
10E

37	10D
38	9E
39	10C
40	11D
41	9C
42	9D
43	11B
44	11C
45	9B
46	10B
47	11A
48	10A
49	9A
50	8B
51	7C
52	6C
53	8A
54	7A
55	7B
56	6B
57	6A
58	5B
59	5A
60	4A
61	5C
62	4B
63	3A
64	2A
65	1A
66	2B
67	3B
68	1C
69	1B
70	3D
71	3C
72	1D

ORDER	PIN ID		
73	2C		
74	3E		
75	2D		
76	2E		
77	1E		
78	2F		
79	3F		
80	1G		
81	1F		
82	3G		
83	2G		
84	1H		
85	1J		
86	2J		
87	3K		
88	3J		
89	2K		
90	1K		
91	2L		
92	3L		
93	1M		
94	1L		
95	3N		
96	3M		
97	1N		
98	2M		
99	3P		
100	2N		
101	2P		
102	1P		
103	3R		
104	4R		
105	4P		
106	5P		
107	5N		
108	5R		
109	Internal		

Note: 1. NC pins are read as "X" (i.e. don't care.)



JTAG DC OPERATING CONDITIONS

Parameter	Symbol	Min	Тур	Max	Unit	Note
Power Supply Voltage	Vdd	1.7	1.8	1.9	V	
Input High Level	VIH	1.3	-	VDD+0.3	V	
Input Low Level	VIL	-0.3	-	0.5	V	
Output High Voltage(IoH=-2mA)	Vон	1.4	-	VDD	V	
Output Low Voltage(IoL=2mA)	Vol	Vss	-	0.4	V	

Note: 1. The input level of SRAM pin is to follow the SRAM DC specification.

JTAG AC TEST CONDITIONS

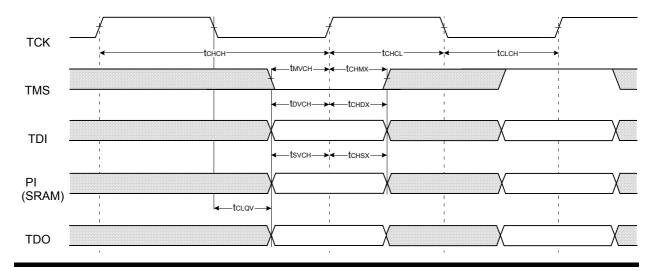
Parameter	Symbol	Min	Unit	Note
Input High/Low Level	VIH/VIL	1.8/0.0	٧	
Input Rise/Fall Time	TR/TF	1.0/1.0	ns	
Input and Output Timing Reference Level		0.9	V	1

Note: 1. See SRAM AC test output load on page 11.

JTAG AC Characteristics

Parameter	Symbol	Min	Max	Unit	Note
TCK Cycle Time	tснсн	50	-	ns	
TCK High Pulse Width	tchcl	20	-	ns	
TCK Low Pulse Width	tclch	20	-	ns	
TMS Input Setup Time	tmvch	5	-	ns	
TMS Input Hold Time	tснмх	5	-	ns	
TDI Input Setup Time	tovch	5	-	ns	
TDI Input Hold Time	tchdx	5	-	ns	
SRAM Input Setup Time	tsvcн	5	-	ns	
SRAM Input Hold Time	tchsx	5	-	ns	
Clock Low to Output Valid	tclav	0	10	ns	

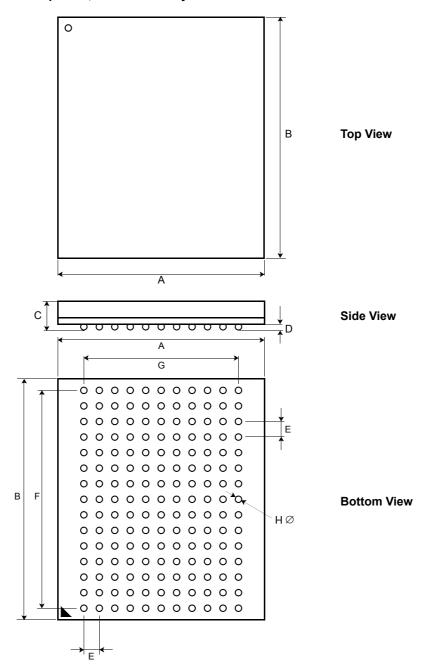
JTAG TIMING DIAGRAM





165 FBGA PACKAGE DIMENSIONS (Lead & Lead-Free)

15mm x 17mm Body, 1.0mm Bump Pitch, 11x15 Ball Array



Symbol	Value	Units	Note	Symbol	Value	Units	Note
Α	15 ± 0.1	mm		E	1.0	mm	
В	17 ± 0.1	mm		F	14.0	mm	
С	1.3 ± 0.1	mm		G	10.0	mm	
D	0.35 ± 0.05	mm		Н	0.5 ± 0.05	mm	

